

# The AVA Multi-View Dataset for Gait Recognition

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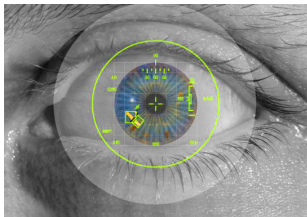
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# Introduction

## Gait Recognition

Human gait as a biometric for identification.

- ▶ Non invasive way to identify people without requiring their cooperation.



## Applications [1]

- ▶ Automation of surveillance,
- ▶ Access control,
  - ▶ Military bases,
  - ▶ Government facilities,
  - ▶ Smart areas,
  - ▶ Bank offices.
- ▶ Human-machine interface,
- ▶ Crowd flux statistics,
- ▶ Detection of anomalous behaviours.

## Gait recognition methods

- ▶ Most gait recognition methods require gait sequences captured from the side view or from the front view of a walking person. [2-6]
- ▶ New challenges in the topic of gait recognition, such as achieving the independence from the camera point of view, usually require multi-view datasets. [7-11]

# Current datasets

- ▶ Single view datasets.
- ▶ Multi-view datasets:
  - ▶ They were recorded in controlled conditions,
  - ▶ Some of them made use of a treadmill,
  - ▶ Most of them lack calibration information.



**Figure :** Samples from CMU Motion of Body (MoBo) [14] and CASIA Dataset B [17].

## Current publicly available datasets

Database	Subset	Type of problem	Subjects	Sequences	Source	Treadmill	Views	Path	Year
UCSD [12]	N.A	Shaded scenes	6	7	Outdoor	No	Side	Circular	1998
HID-UMD [13]	N.A	Undetermined	25	1	Outdoor	No	Front, side	Straight	2001
MoBo [14]	N.A	Multi-view recognition	25	4	Indoor	Yes	Six views	Straight	2001
SOTON [15]	Large	Multiple purposes	100	6	In-outdoor	Some seq.	0, 45, 90	Straight	2002
	Small	Diff. walk. cond.	12	15	Indoor	No	0, 45, 90	Straight	
CASIA	A [16]	Undetermined	20	12	Outdoor	No	0, 45, 90	Straight	2001
	B [17]	Multi-view recognition and diff. carrying cond.	124	10	Indoor	No	11 views	Straight	2005
	C [18]	Diff. walk. cond.	153	10	Outdoor	No	Side	Straight	2005
USF Human ID [19]	N.A	Covariate conditions	122	Up to 5	Outdoor	No	Side	Elliptical	2005
TUM-IITKGP [20]	N.A	Occlusions	35	1	Indoor	No	Side	Straight	2011
OU-ISIR [21]	A	Speed variation	34	68	Indoor	Yes	Side	Straight	2012
	B	Clothes variation	68	Up to 32	Indoor	Yes	Side	Straight	
	D	Gait fluctuation	370	185	Indoor	Yes	Side	Straight	
AVA	N.A	Multi-view recognition	20	10	Indoor	No	Six views	Curved and straight	2013

**Figure : Summary of existing datasets.** Some of the current databases are divided into other subsets, to deal with specific challenges, as clothes variation, carrying conditions, or multiple view gait recognition.

# AVAMVG Multi-View Dataset for Gait Recognition

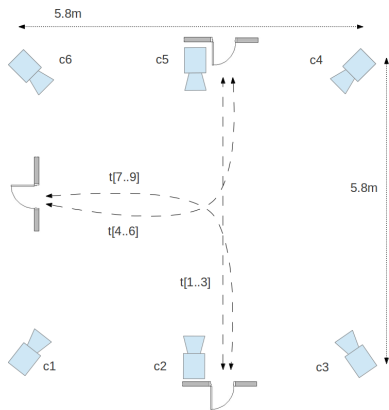
## Features:

- ▶ 20 subjects.
- ▶ 10 sequences by each one.
- ▶ Curved and straight trajectories.
  - ▶ Three straight trajectories.
  - ▶ Six curved trajectories.
  - ▶ A figure-eight trajectory.
- ▶ Was recorded on May 2013.



## Workspace setup for dataset recording

- ▶ 6 IEEE 1394 cameras at a height of 2.3m.
- ▶ Capture volume dimensions  $5m \times 5m \times 2.2m$ .
- ▶ Coverage of a 360 degrees.
- ▶ 4 : 3 format with  $640 \times 480$  at 25Hz.



## Calibration

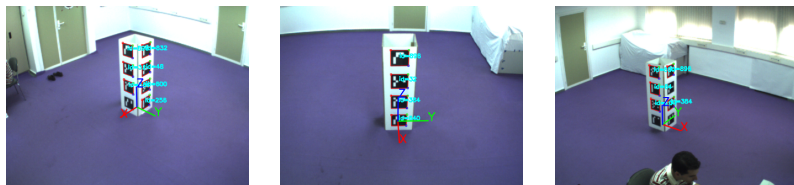


Figure : **3D artifact with Aruco [22] board of markers**, used for getting the pose and orientation of each camera.

## Sample sequences



**Figure :** Example of our multiview dataset. People walking in different directions, from multiple points of view.



## Preprocessing

We have used Horprasert's algorithm [23] to obtain the silhouettes of actors.

- ▶ Is able to detect moving objects in a static background that contains shadows on color images.
- ▶ Is able to deal with local and global perturbation such as:
  - ▶ Illumination changes,
  - ▶ Casted shadows,
  - ▶ Lightening.



# Applications

## Shape from Silhouettes [24]

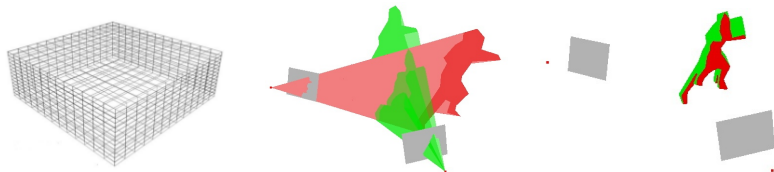
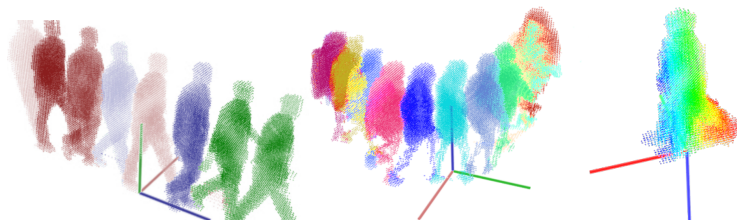


Figure : **Voxelset, silhouette cones, and Visual-Hull**

## Shape from Silhouettes



**Figure :** 3D straight sequence, 3D curve sequence, 3D aligned gait sequence

## Method to test 2D view-dependent gait recognition algorithms on any kind of path

1. Reconstruct all gait sequences by SfS algorithm.
  2. Align and centre them respect to a global reference system.
  3. Use rendered projections of 3D volumes to test 2D-based gait recognition algorithms.
- By this way, we can test view-dependent gait recognition algorithms on any kind of path, either curved or straight.

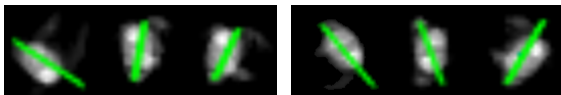
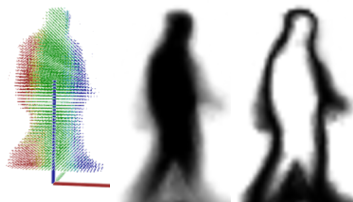


Figure : Principal axis

## Gait recognition based on rendered side images

- ▶ GEI: Gait Energy Image [3], which consists in an average on pixel level of the entire gait sequence.
- ▶ GENI: Gait Entropy Image [5], which encodes in a single image the randomness of pixel values in the silhouette images over a gait cycle.



**Figure :** The reconstructed volumes are aligned along the gait sequence. The two last images show the GEI and GENI computed over rendered images of the aligned sequence, respectively.



## Gait recognition based on frontal-rendered gait images

- ▶ Hold-out experiment.
  - ▶ Gallery set composed by the 1st, 2nd, 4th, 5th, 7th and 8th sequences.
  - ▶ Probe set composed by the 3rd, 6th and 9th sequences.
- ▶ Direct template matching based classifier.

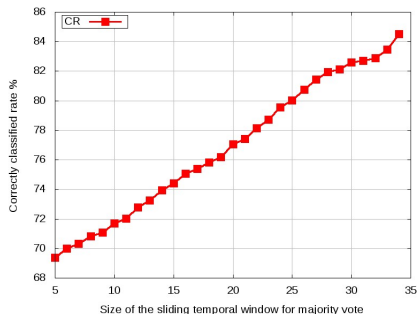
Database	GEI	GEnI
AVA Multiview Dataset	94.6	98.1

**Figure** : Results of the algorithms proposed in [3] and [5] on the AVA Multi-View datasets. We report the recognition rate in %, comparing GEI with GEnI, by direct template matching.

## Gait recognition based on frontal-rendered gait images

- ▶ Video cameras are placed in hallways to capture longer sequences from the front view of walkers rather than the side view.
- ▶ Cover by Rectangles (CR) [6], defined as the union of all the largest rectangles that can fit inside a silhouette. This approach is view-dependent.
- ▶ We can use front-rendered projections of the aligned volumes to compute the CR, and test the method proposed in [6] in a view invariant way.
- ▶ We use a leave-one-out cross-validation, and SVM with Radial Basis Functions.

## Gait recognition based on frontal-rendered gait images



**Figure :** Cover by Rectangles descriptor. Bounding box of a walking human (left), Cover by Rectangles descriptor (center). Recognition rate obtained with the application of the appearance based algorithm proposed in [6] (right). We show the effect on the classification rate of using a sliding temporal window for voting.

# Conclusions

## Conclusions

- ▶ We have presented a new multi-view database containing gait sequences of 20 actors that depict ten different trajectories each (curved and straight)
- ▶ This database has been specifically designed to test multi-view and 3D based gait recognition algorithms.
- ▶ Calibration information and binary silhouettes are also provided.

## Conclusions

- ▶ To validate our database, we have carried out some experiments.
  - ▶ 3D reconstruction of volumes of walking people. Then, we aligned and centred them respect to a global reference system.
  - ▶ We used rendered projections of these volumes to test some appearance-based algorithms that work with silhouettes.
- ▶ The dataset is free only for research purposes.

## Questions time



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